

COSI: CO-simulation model for safety and reliability of electric systems in flexible environment of NPP

Poria Divshali, (VTT) John Millar (Aalto)

28/10/2020 VTT – beyond the obvious





# **Nuclear Power Plant**



#### Combination of several systems

VTT

NORTH

NORTH

# **Nuclear Power Plant Model**



# VTT

# **Nuclear Power Plant Model**





Electric

Motor

Electric

Motor

Fluid

Outlet

Pump

Fluid +





Pumppukuorma: T=kw^2



Internal Electrical System Model

• Each pump model by a Torque (T)

 $T = k \cdot w^2$ 

Pumppukuorma: T=kw^2



Internal Electrical System Model

• Each pump model by a Torque (T)



 Internal Electrical System Model
 Each pump model by a Torque (T) T = k . w^2

• Transmission grid model by Ideal or Thevenin equivalant



 Internal Electrical System Model
 Each pump model by a Torque (T) T = k . w^2

• Transmission grid model by Ideal or Thevenin equivalant





Thermomechanical model

- Apros has electrical system modeling, however limited to
  - Main component models
  - General studies, for example just symetrical studies
  - It is not popular/standard amoung power system experts

# Objective

Provide supporting analyses for safety case:

- A detailed multi-physic simulation model for on-site electric power system of NPP interfaces to the off-site high voltage power system model and to thermal, reactor-physical and automation models.
- COSI will develop plant specific co-simulation models starting with FORTUM's models and integrating later TVO's and possible Fennovoima models.
- The simulation platform will be utilized for evaluation the adequacy and balance of safety requirements of the electrical systems in NPP in the cases of faults and disturbances

# **COSI Project Plan for 2020**





# WP1: COSI Simulation platform architecture

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# **Exchange Layout (1)**

#### Power System Simulator e.g. Simulink

• Turbine / Generator





# **Exchange Layout (3)**

• Pump / Turbine

Power System Simulator e.g. Simulink



#### **Exchange Layout (4)** • Motor (common) Pump Coupling **Power System Simulator** e.g. Simulink $\frac{d}{dt}\omega = \frac{1}{2H} \left( T_e - F\omega - T_m \right)$ $\frac{d}{dt}\theta = \omega$ Rotational speed fT= 98.09 kg/s P\* 0.8ber T= 20.0°C 2.0ber 19.2\*C P<sup>#</sup> rad/sec CM WF YD11D001B1 to round/sec St.CM Tmech YD11D001B <Rotor speed (wm)> CM WF YD11D001B <Electromagnetic torgue Te (N\*m)> CM\_Te\_YD11D001B Asynchronous Machine without saturation1 $\geq$ Mechanical Power 1% Pnom 1 **Apros**

New motor pump operation mode added to Apros

## Co-simulation challenges which should be answered in architecture

- Data Exchange layout among simulators
- Time step handling between simulators

Each Simulator must follow its internal time step, which is totally different in these tools.

# Co-simulation challenges which should be answered in architecture

- Data Exchange layout among simulators
- Time step handling between simulators
- Data exchange intervals between two simulators



## Co-simulation challenges which should be answered in architecture

- Data Exchange layout among simulators
- Time step handling between simulators
- Data exchange intervals between two simulators
- Protocol of data exchange between simulators

# **Protocol of data exchange between simulators**

#### Different simulators in electrical power system of NPP

- MATLAB/Simulink
- PowerFactory DigSILENT
- PSCAD
- . . .

#### **Different simulators in transmission power systems**

- PowerFactory DigSILENT
- PSS/E
- PSCAD
- •
- Apros

Open Platform Communications (OPC) standard

# **Architecture design**



# Co-simulation challenges which should be answered in architecture

- Data Exchange layout among simulators
- Time step handling between simulators
- Data exchange intervals between two simulators
- Protocol of data exchange between simulators
- Initialising of all Simulators in steady-state
  - Load Apros IC
  - Load Simulink IC
  - Start master program from steady-state condition

# **Preliminary Co-Simulation (1)**

#### Power System in Simulink (Generator and Motors)



# **Preliminary Co-Simulation (2)**

#### Turbine and Pumps Models in Apros



25

# **Preliminary Co-Simulation (3)**

Improve the master code to a more user friendly version

• For changing the model need to update just the lay-out file

```
%% Generators Model
% Lavout.GenSet = ( 1)Name , 2) Parameters , 3) Inputs, 4)Output;
% 1)Name : Exact Name in Appros and Simulink
% 2) Parameters: [ 2-1)G PSet ]
   % 2-1)G_PSet_: Initialize seting for Pelectrical (PeoSet) (pu)
% 3) Inputs: [ 3-1)G Pmech ]
   % 3-1)G_Pmech_ : Initialize Mechanical power of Turbine (MW)
% 4) Output: [ 4-1)G_POS_, 4-2)G_W_ ]
   % 4-1)G POS : Initialize valve position
   % 4-2)G W : Initialize rotation speed (RPM)
Layout.GenSet = {'MG0001' 0.9 166.5 [0.51 3000]};
%% BasicPump Model
% Layout.BasicMotor = ( 1) Name , 2) Inputs, 3)Output;
% 1) Name : Exact Name in Appros and Simulink
% 2) Inputs: St.BM_Pmech_...: Initialize Mechanical Power (kW) of Motor
$ 3) Output: BM WP ...: Initialize Speed of Motor (%)
Layout.BasicMotor = {'RM11D001', 15.72, 98.03};
%% CommonFump Model
% Layout.ComMotor = [ 1) Name , 2) Inputs, 3)Output;
                 1 .
```

# **Preliminary Co-Simulation Results (1)**

#### Voltage @ Motor Terminal



# **Preliminary Co-Simulation Results (2)**

#### Motor 1



# **Preliminary Co-Simulation Results (3)**

#### Motor 2



# **Preliminary Co-Simulation Results (4)**



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# **Preliminary Co-Simulation Results (5)**

#### Generator





# WP2: Simulation Study Matti Lehtonen, Aalto

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# **WP 2 Simulation studies**



# VTT

# **Internal grids**

#### Loviisa 1



# **Internal grids**

#### Loviisa 1

#### • Find the steady state condition using separate models



# **Internal grids**

#### Loviisa 1

- Find the steady state condition using separate models
- Update Apros model by adding required transmitter
  - For all motors and Generators

Selecting output component XXXX\_PU1 P\_SPEED\_OLD



Name based on instruction e.g. for basic pump: (speed as in put) BM\_WP\_XXX

rad/sec to round/sec

# **Internal grids**

#### Loviisa 1

• Find the steady state condition using separate models

St.CP\_Tmech

- Update Apros model
- Update Simulink model
  - For all motors and Generators
  - Input

St.CP\_Tmech\_

Name based on instruction e.g. for comon pump: St.CP\_Tmech\_XXX 14/09/2020 VTT – beyond the obvious



rad/sec to round/sec

# **Internal grids**

#### Loviisa 1

• Find the steady state condition using separate models

St.CP\_Tmech

- Update Apros model
- Update Simulink model
  - For all motors and Generators
  - Input

St.CP\_Tmech\_

Name based on instruction e.g. for comon pump: St.CP\_Tmech\_XXX 14/09/2020 VTT – beyond the obvious



# **Internal grids**

#### Loviisa 1

- Find the steady state condition using separate models
- Update Apros model
- Update Simulink model
- Update the layour file in master program

```
%% Generators Model
% Layout.GenSet = { 1)Name , 2) Parameters , 3) Inputs, 4)Output;
% 1)Name : Exact Name in Appros and Simulink
% 2) Parameters: [ 2-1)G PSet ]
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% 3) Output: BM WP ...: Initialize Speed of Motor (%)
Layout.BasicMotor = {'RM11D001', 15.72, 98.03};
%% CommonPump Model
% Layout.ComMotor = [ 1) Name , 2) Inputs, 3) Output;
```

1 .



# COSI – recent Aalto activities

# So far

#### • Brushing up on transmission system basics

- Modelling nodes
- Modelling lines
- 3-phase power flow basics, noting that we will be dealing with asymmetric scenarios
- Gleaning Fingrid data from QGIS-related files (→Excel (done) →some other database format?)
- Learning and slowly building up a simple network in Simulink (some 'steady-state' success)



#### Possible directions for transmission model development



Aalto University School of Electrical Engineering

How far we get in this roadmap will depend on time and benefit - noting that we are aiming for minimum sufficient transmission models that are relevant to the nuclear power station of interest.

# **Visualising data in QGIS**



# Data has been extracted from QGIS (&/or .dbf files and Energiavirasto)

#### Line data

1											
2		1:load,	2:generator,	3: Swing, 4:	disconnect	ed bus		WGS84			
3	bus_id	type	station_id	voltage	name	Station name	comments	×	Y	pl	ql
4	20101	2	234	110	KS1	KRISTIINA		21.33021	62.255	50.2176	8.03482
5	20016	4	279	110		FLYB-CKIN HAARA	Not connected	21.37614	62.292	97.829	15.6526
6	20352	2	356	110	KD	KRISTINESTAD		21.37629	62.292	17.0222	2.72355
7	30074	1	356	21	KD_TER1	KRISTINESTAD	Needed if there will be a 3- winding transformer in Kristinestad.	21.37629	62.292	84.4881	13.5181
8	5018	1	356	400	KD4	KRISTINESTAD		21.37629	62.292	#N/A	#N/A
9	4163	2	145	400	MP4	TAHKOLUOTO	Added this bus to TAHKOLUOTO station, Erkka	21.40762	61.633	#N/A	#N/A
0	20355	2	145	110		TAHKOLUOTO	Added this bus for Tahkoluoto KT-laitos (Niina Helistö).	21.40762	61.633	151.368	24.2189
1	20278	4	62	110		TORNA	Not connected	21.40798	61.042	15.0296	2.40474
12	20349	2	240	110	OLT1	OLKILUODON KT-LAITOS	Slack bus for COSI purposes?	21.44494	61.24	8.5063	1.36101
3	4160	2	27	400	OL4	OLKILUOTO		21.4712	61.245	#N/A	#N/A
	4168	2	27	400	OL42	OLKILUOTO		21.4712	61.245	#N/A	#N/A







This thesis used a 57 node model for the Nordics http://kth.di

http://kth.diva-portal.org/smash/get/diva2:1369967/FULLTEXT01.pdf





#### It would be nice to start simple!



But, the generation in the (8-bus) Finnish part of the 57-bus network is perhaps too scenario-specific, but a good first approximation?



TENCINE.

1.1.2017 Pohjakartta © Karttakeskus Oy

# **Conclusion, for WP2**

- Model the 400 kV grid of Finland and any necessary sections of lower voltage transmission
- We have the data for that
- But it will be quite tedious modelling it all in Simulink – but great once we've done it!
- Check modelling with another platform
- Simulations and case studies!

#### FINGRID





# beyond the obvious

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