DESIGN OF A BUOYANT AND AUTONOMOUS PRESSURE SENSOR FOR IN-SITU TUNNEL MEASUREMENTS

Robin Andersson Luleå Tekniska Universitet Division of Fluid and Experimental Mechanics



The conundrum of hydropower tunnels

- Present methods of evaluation are old and crude
- All Hydropower tunnels suffer from rock falls, some suffer worse fates! Why?
- Several options:
 - Numerical modelling
 - Experimental studies
 - Field measurements



Example: Gävunda Hydropower tunnel 23200 3000 LULE 501 7000 TEKNISKA UNIVERSITET





What are the implications on the flow?



Tunnelsensor, why?

- Cheap alternative to current methods of evaluation
 - ROV
 - Decomissioning of the tunnel in question
- Possibility to continously screen the tunnels durability (To discover changes over time)



Probe requirements

- Boyant
- Affordable
- Retreivable
- Easy to use



- Main board: Arduino Nano (ATmega328 processor)
- Accelerometer (IMU): BNO055
- Data storage: Adafruit micro-SD card breakout board
- Time measurement (Quartz based): PCF8523 Real Time Clock (RTC)
- Pressure sensor: Leveline mini
- Total price around 600 euros











Algorithms

- To avoid Gimbal-lock we use Quaternions
- The IMU already has several algorithms for calculating the relative heading
- For redundancy we have added our own algorithms as following

Evaluating the Algorithms





Summary



- Evaluation of hardware took alot of time
 - Covid created long delivery-times
- Pressure sensor requires different approach
- Total cost of the probe is around 6000 SEK
- A Watertight shell and recovery system still needs to be constructed
- Large-scale tests remains to be conducted



Thank you!

